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# Even pairs in square-free Berge graphs

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#### Abstract

This is a short example to show the basics of using the ENDM style macro files. Ample examples of how files should look may be found among the published volumes of the series at the ENDM home page (http://www.elsevier.com/locate/endm)

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## 1 Introduction

A graph G is *perfect* if every induced subgraph H of G satisfies  $\chi(H) = \omega(H)$ , where  $\chi(H)$  is the chromatic number of H and  $\omega(H)$  is the maximum clique size in H. A hole is a chordless cycle with at least four vertices and an *anti*hole is the complement of a hole. A *Berge graph* is any graph that contains no odd hole and no odd antihole of length at least 5. Berge's famous "Strong Perfect Graph Conjecture" [1,2,3,12] was solved by Chudnovsky, Robertson, Seymour and Thomas [6]: *Every Berge graph is perfect*. Moreover, Chudnovsky, Cornuéjols, Liu, Seymour and Vušković [5] devised a polynomial-time algorithm that determines if a graph is Berge. It is known that one can obtain an optimal coloring of a perfect graph in polynomial time due to the algorithm

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of Grötschel, Lovász and Schrijver [9]. This algorithm however is not purely combinatorial and is generally considered impractical.

An even pair in a graph G is a pair  $\{x, y\}$  of non-adjacent vertices such that every chordless path between them has even length (number of edges). A graph G is even-contractile [4] if either G is a clique or there exists a sequence  $G_0, \ldots, G_k$  of graphs such that  $G = G_0$ , for  $i = 0, \ldots, k - 1$  the graph  $G_i$  has an even pair  $\{x_i, y_i\}, G_{i+1}$  is the graph obtained from  $G_i$  by contracting (identifying)  $x_i$  and  $y_i$  into one vertex, and  $G_k$  is a clique. A graph G is perfectly contractile if every induced subgraph of G is even-contractile. This class is of interest because many classical families of graphs are perfectly contractile and consequently admit a "purely combinatorial" coloring algorithm; see [8].

Everett and Reed [8] proposed a conjecture aiming at a characterization of perfectly contractile graphs. A *prism* is a graph that consists of two vertexdisjoint triangles (cliques of size 3) with three vertex-disjoint paths  $P_1, P_2, P_3$ between them, and with no other edge than those in the two triangles and in the three paths. The length of a path is its number of edges. Note that if two of the paths  $P_1, P_2, P_3$  have lengths of different parities, then their union induces an odd hole. So in a Berge graph, the three paths of a prism have the same parity. A prism is *even* (resp. *odd*) if these three paths all have even lengths (resp. all have odd lengths).

**Conjecture 1.1 ([8])** A graph is perfectly contractile if and only if it contains no odd hole, no antihole of length at least 5, and no odd prism.

**Conjecture 1.2** ([8]) Any graph that contains no odd hole, no antihole of length at least 5, and no prism is perfectly contractile.

Conjecture 1.1 remains open. Let  $\mathcal{A}$  be the class of graphs that contain no odd hole, no antihole of length at least 5, and no prism. Conjecture 1.2 was proved in [11], as follows.

**Theorem 1.3** ([11]) There is a polynomial time algorithm which returns a clique of size  $\omega(G)$  and a coloring with  $\omega(G)$  colors for every graph G in  $\mathcal{A}$ .

A square is a hole of length four. A graph is square-free if it does not contain a square as an induced subgraph. We will be able to prove that every square-free Berge graph with no odd prism either is a clique or has an even pair, as suggested in Conjecture 1.1. Unfortunately, contracting an even pair may result in the presence of a square in the contracted graph, so the result does not yield a proof of Conjecture 1.1 for square-free graphs. Nevertheless, using the presence of even pairs, we can prove the following theorem.

**Theorem 1.4** There exists a combinatorial and polynomial time algorithm which, given any square-free Berge graph G with no odd prism, returns an  $\omega(G)$  coloring of G and a clique of size  $\omega(G)$ .

Since Theorem 1.3 settles the case of graphs that have no prism, we may assume from now on that we are dealing with a square-free Berge graph G that contains no odd prism and contains an even prism.

## 2 Hyperprisms

Given a set  $T \subset V(G)$ , we say that a vertex of  $V(G) \setminus T$  is complete to T if it is adjacent to all vertices of T. Given two sets  $S, T \subset V(G)$ , S is complete to T if every vertex of S is complete to T.

As in [6], a hyperprism is a 9-tuple  $(A_1, C_1, B_1, A_2, C_2, B_2, A_3, C_3, B_3)$  of non-empty and pairwise disjoint subsets of V(G) with the following properties:

- For distinct  $i, j \in \{1, 2, 3\}$ ,  $A_i$  is complete to  $A_j$ , and  $B_i$  is complete to  $B_j$ , and there are no other edges between  $A_i \cup C_i \cup B_i$  and  $A_j \cup C_j \cup B_j$ .
- For each  $i \in \{1, 2, 3\}$ , every vertex of  $A_i \cup C_i \cup B_i$  belongs to a chordless path between  $A_i$  and  $B_i$  with interior in  $C_i$ .

For each  $i \in \{1, 2, 3\}$ , a chordless path from  $A_i$  to  $B_i$  with interior in  $C_i$  is called an *i*-rung. Let us write  $A = A_1 \cup A_2 \cup A_3$ ,  $B = B_1 \cup B_2 \cup B_3$  and  $C = C_1 \cup C_2 \cup C_3$ . Let  $S_i = A_i \cup B_i \cup C_i$  for  $i \in \{1, 2, 3\}$ . The triple  $(A_i, C_i, B_i)$  is called a *strip* of the hyperprism. We call (A, C, B) the *profile* of the hyperprism. Given two hyperprisms  $\eta$  and  $\eta'$  with profiles (A, C, B)and (A', C', B') respectively, we write  $\eta \prec \eta'$  if  $C \subseteq C'$  and either (i)  $A \subseteq A'$ and  $B \subseteq B'$  or (ii)  $A \subseteq B'$  and  $B \subseteq A'$  and one of these inclusions is strict. Clearly,  $\prec$  is an order relation on hyperprisms, so we can speak about maximal hyperprisms for  $\prec$ .

Let  $\eta$  be a maximal hyperprism. Let H be the subgraph of G induced on the union of the nine sets  $A_i, B_i, C_i, i = 1, 2, 3$ . If we pick any *i*-rung  $R_i$  for each  $i \in \{1, 2, 3\}$ , with ends  $a_i \in A_i$  and  $b_i \in B_i$ , we see that  $R_1, R_2, R_3$  form a prism K; any such prism is called an *instance* of the hyperprism. A vertex x in  $V(G) \setminus V(K)$  is a *major* neighbor of K if x has at least two neighbors in  $\{a_1, a_2, a_3\}$  and at least two neighbors in  $\{b_1, b_2, b_3\}$ . A vertex x in  $V(G) \setminus V(H)$ is a *major* neighbor of H if x is a major neighbor of an instance of  $\eta$ . Let Mbe the set of all major neighbors of H.

Lemma 2.1 The following properties hold:

• M is a clique.

• For each  $i \in \{1,2,3\}$ ,  $M \cup A_i \cup B_i$  is a cutset that separates  $C_i$  from  $S_{i+1} \cup S_{i+2}$ .

- Two of  $A_1, A_2, A_3$  and two of  $B_1, B_2, B_3$  are cliques.
- M is complete to at least two of  $A_1, A_2, A_3$  and at least two of  $B_1, B_2, B_3$ .

• There is an integer  $j \in \{1, 2, 3\}$  such that  $A_j$  and  $B_j$  are cliques and M is complete to  $A_j \cup B_j$ .

#### 2.1 Selecting a strip

Let us say that a strip  $(A_i, C_i, B_i)$  of the hyperprism is good if both  $A_i$  and  $B_i$  are cliques and M is complete to  $A_i \cup B_i$ . Lemma 2.1 says that every maximal hyperprism in G has a good strip. We may assume that  $(A_1, C_1, B_1)$  is a good strip of  $\eta$ . Moreover, we choose  $\eta$  such that  $S_1$  has the smallest size over all good strips of maximal hyperprisms.

Let R' and R'' be two 1-rungs of  $\eta$ , where R' has ends u', w, and R'' has ends u'', w, and  $u' \neq u''$  (so w is in one of the two sets  $A_1, B_1$  and u', u'' are in the other set). We say that R' and R'' converge if u' has no neighbor in  $R'' \setminus u''$  and u'' has no neighbor in  $R' \setminus u'$ .

#### Lemma 2.2 There do not exist two 1-rungs that converge.

*Proof.* In the opposite case, we are able to construct a maximal hyperprism  $\eta'$  that has a smaller good strip than  $\eta$ , a contradiction to the choice of  $\eta$ .  $\Box$ 

#### 2.2 Finding an even pair

Consider any  $b \in B_1$ . For any two  $a, a' \in A_1$ , write  $a <_b a'$  whenever there exists an odd chordless path R from a to b such that a' is the neighbor of a on R. For each  $a \in A_1$  define similarly a relation  $<_a$  on  $B_1$ .

**Lemma 2.3** For each  $b \in B_1$ ,  $<_b$  is an order relation.

*Proof.* In the opposite case, we are able to find two 1-rungs that converge.  $\Box$ 

Using Lemma 2.3 and its analogue for every vertex in  $A_1 \cup B_1$ , we can establish the following.

**Lemma 2.4** There exists an even pair  $\{a, b\}$  of G with  $a \in A_1$  and  $b \in B_1$ .

Let  $A_1 = \{a_1, \ldots, a_k\}$  and  $B_1 = \{b_1, \ldots, b_\ell\}$ , and assume that  $k \leq \ell$ . By Lemma 2.4, we may assume that  $\{a_1, b_1\}$  is an even pair of G; and similarly, for  $i = 2, \ldots, k$ , we may assume that  $\{a_i, b_i\}$  is an even pair of  $G \setminus \{a_1, b_1, \ldots, a_{i-1}, b_{i-1}\}$ .

#### 2.3 Decomposing the graph

By Lemma 2.1,  $V(G) \setminus (M \cup A_1 \cup B_1)$  can be partitioned into two subsets Xand Y, with  $C_1 \subseteq X$  and  $C_2 \subset Y$ , such that there is no edge between X and Y. Let  $G_X = G \setminus Y$  and  $G_Y = G \setminus X$ . Thus we consider that G is decomposed into  $G_X$  and  $G_Y$ . Since  $G_X$  and  $G_Y$  are proper induced sugraphs of G, we may assume by induction that we have a clique  $Q_X$  of  $G_X$  of size  $\omega(G_X)$  and a coloring  $c_X$  of  $G_X$  with  $\omega(G_X)$  colors, and the same for  $G_Y$ .

**Lemma 2.5** There exists a coloring  $c'_X$  of  $G_X$  with  $\omega(G_X)$  colors such that  $c'_X(a_i) = c'_X(b_i)$  for all i = 1, ..., k, and such a coloring can be obtained from  $c_X$  in polynomial time.

Proof. Suppose that  $c_X$  itself does not have the desired property, and let h be the smallest integer such that  $c_X(a_h) \neq c_X(b_h)$ . In case h > 1, we may assume, up to relabeling, that  $c_X(a_i) = i = c_X(b_i)$  for all  $i = 1, \ldots, h - 1$ . Let  $c_X(a_h) = i$  and  $c_X(b_h) = j$ , with  $i \neq j$ . Let W be the bipartite subgraph of G induced by the vertices of color i and j. We swap colors i and j in the component of W that contains  $a_h$ . This component does not contain  $b_h$ , for otherwise it contains a chordless odd path between  $a_h$  and  $b_h$ , and this path is in  $G \setminus \{a_1, b_1, \ldots, a_{h-1}, b_{h-1}\}$  since it contains no vertex of color less than i and j; but this contradicts the fact that  $\{a_h, b_h\}$  is an even pair of  $G \setminus \{a_1, b_1, \ldots, a_{h-1}, b_{h-1}\}$ . So, after the swap,  $a_h$  and  $b_h$  have the same color. Thus we obtain a coloring of  $G_X$  with  $\omega(G_X)$  colors where the value of h has increased. Repeating this procedure at most k times leads to the desired coloring.

Applying Lemma 2.5 to both  $G_X$  and  $G_Y$ , we obtain colorings  $c_X$  and  $c_Y$ of  $G_X$  and  $G_Y$  respectively such that, up to relabeling,  $c_X(a_i) = c_X(b_i) = c_Y(a_i) = c_Y(b_i)$  for each  $i = 1, \ldots, k$ . By Lemma 2.1,  $M \cup (B \setminus \{b_1, \ldots, b_k\})$  is a clique and all its vertices are adjacent to  $b_i$  for each  $i = 1, \ldots, k$ . So we may assume that every vertex z in  $M \cup (B \setminus \{b_1, \ldots, b_k\})$  satisfies  $c_X(z) = c_Y(z)$ . Thus the two colorings  $c_X$  and  $c_Y$  coincide on the cutset  $M \cup A_1 \cup B_1$  and so they can be merged into a coloring of G. This coloring uses  $\max\{\omega(G_X), \omega(G_Y)\}$ colors, and one of  $Q_X$  and  $Q_Y$  is a clique of that size. So the coloring and the larger of these two cliques are both optimal.

## 3 The algorithm

We can now describe our algorithm. Let  $\mathcal{G}$  be the class of square-free Berge graphs with no odd prism.

Input: A graph G on n vertices.

**Output:** Either a coloring of G and a clique of the same size, or the negative answer "G is not in  $\mathcal{G}$ ".

**Step 1.** Test whether G is square-free, and test whether G is Berge with the algorithm from [5]. If any of these tests fails, return the answer "G is not in  $\mathcal{G}$ " and stop. Now test whether G contains a prism as explained in [10]. If this algorithm produces an odd prism, then return the negative answer and stop; if it shows that G contains no prism, then color G applying the algorithm from [11].

**Step 2.** Now suppose that Step 1 has produced an even prism. Grow a maximal hyperprism  $\eta$ , and find a good strip  $S_1$  of  $\eta$ .

Apply Lemma 2.3 to each vertex  $x \in A_1 \cup B_1$ . Its proof either establishes that  $<_x$  is an order relation or finds 1-rungs that converge; in the latter case, the proof of Lemma 2.2 produces a new maximal hyperprism  $\eta'$  with a smaller good strip; then restart from  $\eta'$ .

When  $<_x$  is an order relation for all  $x \in A_1 \cup B_1$ , Lemma 2.4 shows how to find even pairs. The graph G is decomposed into graphs  $G_X$  and  $G_Y$ , and an optimal coloring and a maximal clique for G can be obtained as explained above.

#### 3.1 Complexity analysis

We can test whether a graph G is Berge in time  $O(n^9)$  with the algorithm from [5]. We can test whether G is square-free in time  $O(n^4)$ , and whether a Berge graph G contains a prism in time  $O(n^5)$  as explained in [10]. Now assume that the algorithm produces an even prism. It is easy to to see that all the procedures in Step 2 of the algorithm (growing a maximal hyperprism, determining the orderings) can be performed in time at most  $O(n^3)$ . We complete our analysis with two remarks.

(a) When we restart from a new hyperprism, the size of the good strip is strictly smaller; so this restarting step occurs at most O(n) times.

(b) When G is decomposed into graphs  $G_X$  and  $G_Y$ , the algorithm is called recursively on them. This corresponds to a decomposition tree T for G: every non-leaf node of T is an induced subgraph G' of G and has two children which are induced subgraphs of G'; and every leaf of T is a graph that contains no prism. Let us show that this tree has polynomial size. When G is decomposed into graphs  $G_X$  and  $G_Y$  as above, because of a certain cutset that arises from a hyperprism  $\eta$ , we mark the corresponding node of the tree with a pair of vertices  $\{c_1, c_2\}$  where  $c_1 \in C_1$  and  $c_2 \in C_2$  are chosen arbitrarily. We mark every subsequent decomposition node similarly. We can show the following.

**Lemma 3.1** Every pair of vertices of G is used to mark at most one node of the decomposition tree.

By Lemma 3.1 the total number of nodes in T is  $O(n^2)$ . The leaves of the decomposition tree T are Berge graphs with no antihole (since they are square-free) and no prism, so they can be colored in time  $O(n^6)$  as explained in [11]. At each node G' of T different from the root G, we know that G' is an induced subgraph of G, so it is a square-free Berge graph; hence we must only test whether G' contains a prism, which is done in time  $O(n^5)$  as explained in [10]. So the total complexity of the algorithm is  $O(n^9 + n^2 \times n^5 + n^2 \times n^6)$  $= O(n^9)$ .

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